



# **SCARA ROBOT**

# ACT06-602S ACT06-702S

Fast, accurate and reliable.
Suitable for pick-n-place of 3C industry.

## **Robot specifications**

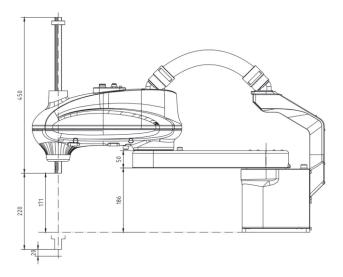
Basic data	
Model No.	ACT06-602S/ACT06-702S
Number of axes	4
Maximum payload	6 kg
Maximum stroke	600/700mm
IP class	J1, J2 - IP56; J3, J4- IP67
Mounting position	Floor type
Approx. weight	30 kg (without cabinet)
Repeatability	±0.02 mm
Internal air duct	Ф6
Motion range	
J1 axis S	±132°
J2 axis L	±150°
J3 axis U	220mm
J4 axis R	±360°
Speed with rated payload	
J1 axis S	540°/s
J2 axis L	600°/s
J3 axis U	750°/s
J4 axis R	1717 °/s

Electrical cabinet specifications	
Dimensions	490*400*365mm
Approx. weight	40KG
Cooling method	Natural cooling
Input power	220VAC 50/60Hz
Grounding	Industrial grounding (grounding resistance below $100\Omega$ )
	·16 digital inputs
I/O terminals	·16 digital outputs
	·2 analog outputs (optional)
Position control mode	EtherCAT, TCP/IP
Serial port I/F	RS485*1, RS422*1, RS232*1, CAN*1, USB*1
RAM capacity	JOB 200,000 steps, 10,000 robot commands (200MB)
Driving unit	6-axis AC servo system. External axis can be added as an option.

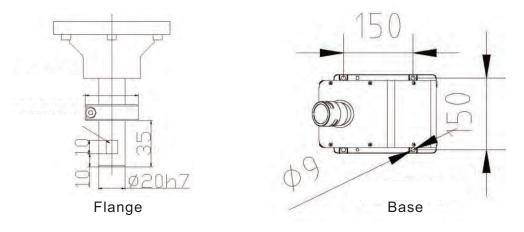
Operating conditions	
Use temperature	0~45°C
Storage temperature	-20~60°C
Humidity	10~90% RH, no condensing
Vibrations	Below 0.5G
Altitude	Below 1000m. (Degrade if over 1000m, max 2000m)
Other requirements	With no corrosive or combustible gas     With no water, oil or drug splashing     With no electromagnetic field nearby     With no radiations nearby



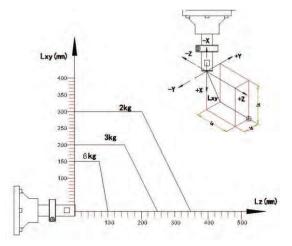
## ▶ Working envelope (unit: mm)



#### Flange and base dimensions (unit: mm)



#### ▶ Payload diagram



All data, drawings and specifications provided in this catalog are purely for information purposes and do not constitute a guarantee of these characteristics. The extent of goods delivered and services performed is determined by the subject matter of the specific contract. No liability accepted for errors or omissions.